



# Model PC420A-B3223 Frequency-banded acceleration loop powered sensors (LPS™)

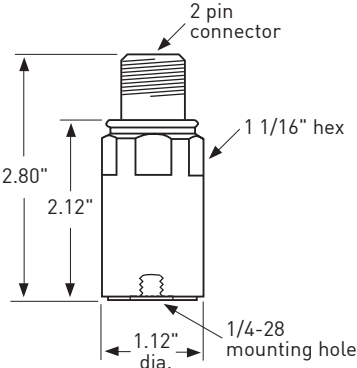
**Features**

- True RMS or true peak output
- Corrosion resistant
- Hermetic seal
- ESD protection
- Overload protection
- Reverse wiring protection

**Benefits**

- Much-narrower bandwidth with higher-order filtering limits fundamental frequencies
- Designed to examine frequencies related to pump cavitation
- Provides continuous trending of overall machine vibration
- Can help guide maintenance
- Helps notify of impending equipment failure

The 4-20 mA output of the frequency-banded accelerometer is proportional to acceleration vibration. An output of 4 mA indicates a level of 0g or no vibration present. A full-scale reading of 20 mA indicates that the maximum range of vibration is present. This sensor filters-out low frequency components, such as motor running speed, in favor of higher frequency information related to pump cavitation. Higher order filtering sharpens sensor bandwidth for tight performance.



**Output, 4-20 mA**

Full scale, 20 mA (±5%) .....	see table 1
Frequency response:	
±10% .....	400 Hz - 1.4 kHz
±3 dB .....	300 Hz - 2 kHz
Repeatability .....	±2%
Transverse sensitivity, max. ....	5%

**Electrical**

Power requirements (two wire loop power):

Voltage at PC420 Series sensor terminals.....	10 VDC min, 30 VDC max
Loop resistance <sup>1</sup> at 24 VDC, maximum .....	700Ω
Turn on time, 4-20 mA loop .....	< 30 seconds
Grounding.....	case isolated, internally shielded

**Environmental**

Temperature range .....	-40 to 85°C
Vibration limit .....	250 g peak
Shock limit .....	2,500 g peak
Sealing .....	hermetic

**Physical**

Sensing element design .....	PZT ceramic / shear
Weight .....	162 grams
Case material.....	316L stainless steel
Mounting .....	1/4 - 28 tapped hole
Output connector .....	2 pin, MIL-C-5015 style
Mating connector .....	R6 type
Recommended cabling .....	J9T2A

Connector pin	Function
Shell	ground
A	loop positive (+)
B	loop negative (-)

Notes: <sup>1</sup> Maximum loop resistance (R<sub>L</sub>) can be calculated using formula on back. Accessories supplied: SF6 mounting stud (International customers specify mounting requirements); calibration data (level 2).

See back for table 1 and powering diagram.

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Table 1: PC420Axx-yy-B3223

xx (4-20 mA output type)	yy (4-20mA full scale)
R = RMS output, acceleration	05 = 5 g
P= equivalent peak output, acceleration	10 = 10 g
TP= true peak output, acceleration	20 = 20 g

Notes:

<sup>1</sup> Maximum loop resistance calculation:

$$R_L \text{ (max resistance)} = \frac{V_{\text{DC power}} - 10 \text{ V}}{20 \text{ mA}}$$

DC supply voltage	$R_L$ (max resistance) <sup>2</sup>	$R_L$ (minimum wattage capability) <sup>3</sup>
12 VDC	100Ω	1/8 Watt
20 VDC	500Ω	1/4 Watt
24 VDC	700Ω	1/2 Watt
26 VDC	800Ω	1/2 Watt
30 VDC	1.0kΩ	1/2 Watt

<sup>2</sup> Lower resistance is allowed, greater than 10Ω recommended.

<sup>3</sup> Minimum  $R_L$  wattage determined by:  $(0.0004 \times R_L)$ .

Typical circuit

